DLSG #4 - Convolutional Neural Networks

DLSG

25 November, 2016

DLSG #4 - Convolutional Neural Networks









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Housekeeping

- Next session?
- Feedback so far?

Big Schedule Review

- Introduction to Keras
- (Artificial) Neural Networks and their training
- Convolutional Neural Networks
- Recurrent Neural Networks
- Neural Networks in Computer Vision
- Neural Networks in Natural Language Processing

 iSee: Using deep learning to remove eyeglasses from faces https://blog.insightdatascience.com/ isee-removing-eyeglasses-from-faces-using-deep-learning .86qddOmqu

- iSee: Using deep learning to remove eyeglasses from faces https://blog.insightdatascience.com/ isee-removing-eyeglasses-from-faces-using-deep-learning .86qddOmqu
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- Lip Reading Sentences in the Wild https://www.youtube.com/watch?v=5aogzAUPilE
- Interactive convnet features visualization for Keras https://github.com/jakebian/quiver https: //www.youtube.com/watch?edit=vd&v=tgRW3BRi_FA

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- Lip Reading Sentences in the Wild https://www.youtube.com/watch?v=5aogzAUPilE
- Interactive convnet features visualization for Keras https://github.com/jakebian/quiver https: //www.youtube.com/watch?edit=vd&v=tgRW3BRi_FA
- Image-to-Image Translation with Conditional Adversarial Nets https://phillipi.github.io/pix2pix/

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ConvNets

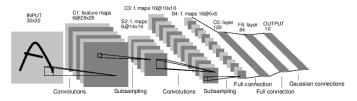
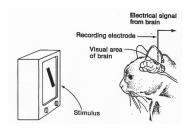


Figure: LeNet [LeCun et al., 1998]

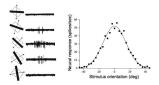
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Hubel & Wiesel

1959 - Receptive fields of single neurones in the cat's striate cortex 1962 - Receptive fields, binocular interaction and functional architecture in the cat's visual cortex



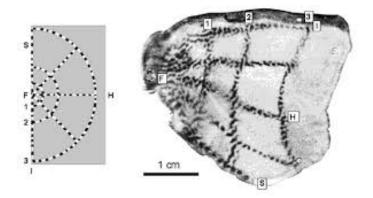
V1 physiology: orientation selectivity



Hubel & Wiesel, 1968

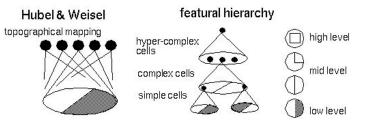
A bit of history

Topographical mapping in the cortex: nearby cells in cortex represented nearby regions in the visual field



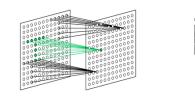
A bit of history

Hierarchical organization



A bit of history

Neurocognitron [Fukushima 1980]: "sandwich" architecture (SCSCSC...) simple cells: modifiable parameters complex cells: perform pooling



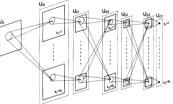


Figure: Neurocognitron [Fukushima 1980]

LeNet

Gradient-based learning applied to document recognition

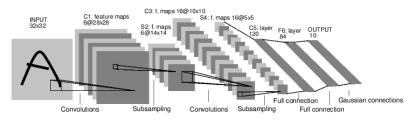


Figure: LeNet [LeCun, Bottou, Bengio, Haffner 1998]

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AlexNet

ImageNet Classification with Deep Convolutional Neural Networks

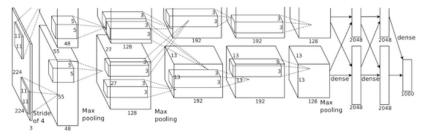


Figure: AlexNet [Krizhevsky, Sutskever, Hinton, 2012]

ResNet

Depth Revolution

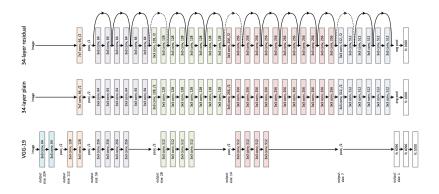


Figure: ResNet [Kaiming He, Xiangyu Zhang, Shaoqing Ren, Jian Sun, 2015]

Classification

Retrieval

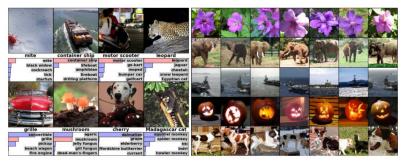


Figure: [Krizhevsky 2012]

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Detection



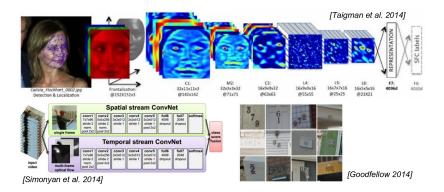


Figure: [Faster R-CNN: Ren, He, Girshick, Sun 2015] Detection Segmentation & [Farabet et al., 2012]





Figure: Self driving cars



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[Toshev, Szegedy 2014]



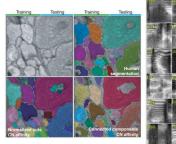
[Mnih 2013]



[Ciresan et al. 2013]

[Sermanet et al. 2011] [Ciresan et al.]

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[Turaga et al., 2010]

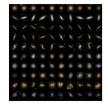
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Whale recognition, Kaggle Challenge



Mnih and Hinton, 2010

ConvNets today





reddit.com/r/deepdream

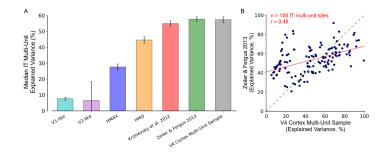


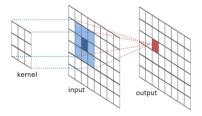
Figure: Deep Neural Networks Rival the Representation of Primate IT Cortex for Core Visual Object Recognition [Cadieu et al., 2014]

Convolution

So what is "convolution"

Convolution

So what is "convolution"



2D Convolution



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Convolution

 $\sum_{i=1}^n x_i w_i$

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Convolution

$$\sum_{i=1}^n x_i w_i = X \cdot W$$

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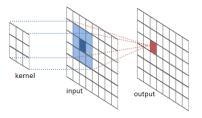
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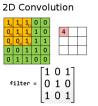
Convolution

$$(f * g)[n] = \sum_{m=-\infty}^{\infty} f(m)g(n-m)$$

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Convolution





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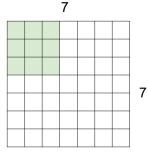
Convolution

We don't have to go with stride $1 \$

ConvNets

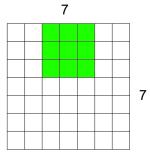
Convolution

We don't have to go with stride 1



7x7 input (spatially) assume 3x3 filter applied **with stride 2**

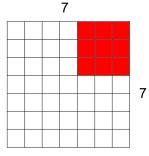
Convolution



7x7 input (spatially) assume 3x3 filter applied **with stride 2**

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Convolution

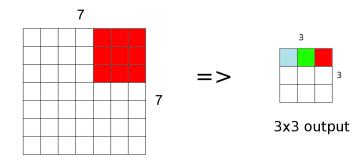


7x7 input (spatially) assume 3x3 filter applied **with stride 2**

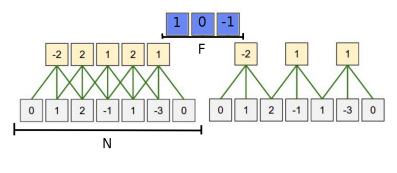
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${\sf Convolution}$



Convolution



Output size:
$$\frac{N-F}{stride} + 1$$

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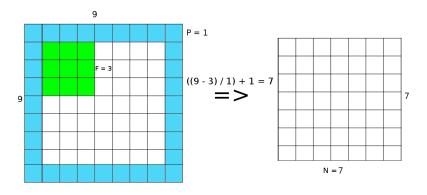
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${\sf Convolution}$

What if I want to keep spatial dimension?

Convolution

What if I want to keep spatial dimension? Pad the input!

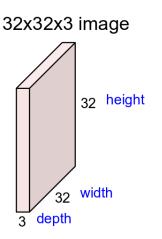


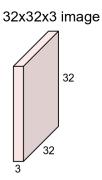
Output size:
$$\frac{N-F+2P}{stride} + 1$$

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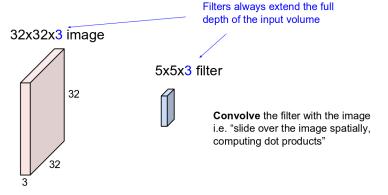


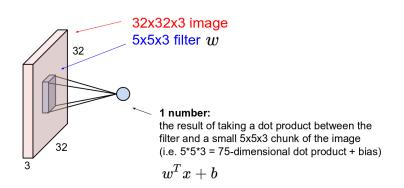


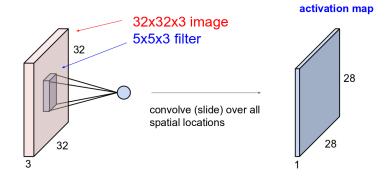
5x5x3 filter



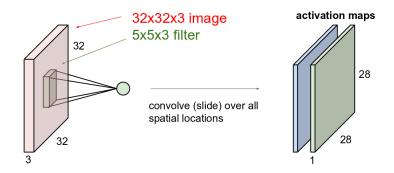
Convolve the filter with the image i.e. "slide over the image spatially, computing dot products"



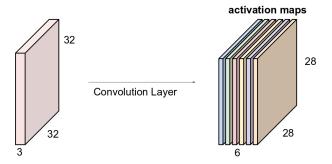




consider a second, green filter



For example, if we had 6 5x5 filters, we'll get 6 separate activation maps:

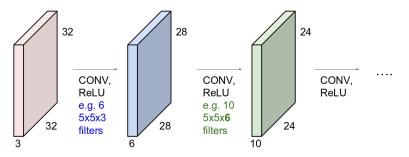


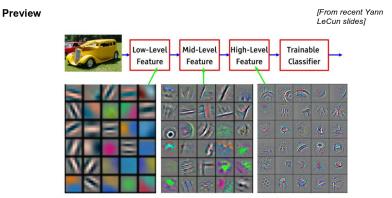
We stack these up to get a "new image" of size 28x28x6!

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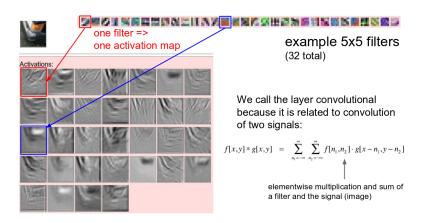
Convolution layer

Preview: ConvNet is a sequence of Convolutional Layers, interspersed with activation functions



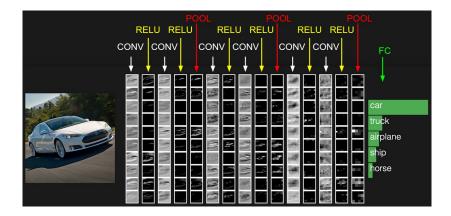


Feature visualization of convolutional net trained on ImageNet from [Zeiler & Fergus 2013]



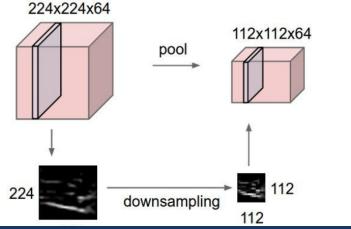
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Convolutional Neural Network



Pooling layer

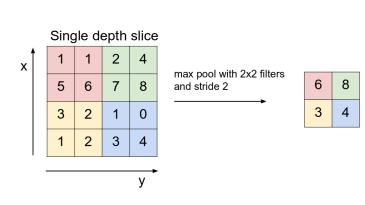
- makes the representations smaller and more manageable
- operates over each activation map independently:



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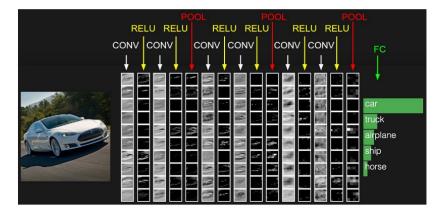
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Max pool



Fully Connected layers

Contains neuurons that connect to the entire input volume, as in ordinary NN



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Final words

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Final words

- http://dlsg.naiveneuron.com
- ...

References

- cs231n.stanford.edu/slides/winter1516_lecture6.pdf
- cs231n.stanford.edu/slides/winter1516_lecture7.pdf
- cs231n.github.io/
- IRC server freenode channel #naiveneuron